

Modeling and simulation of the non-equilibrium process for a continuous solid-solution system in lithium-ion batteries

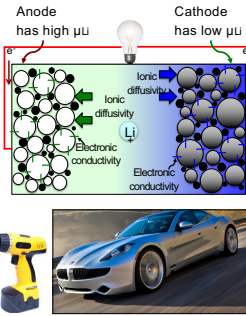
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Introduction and Background

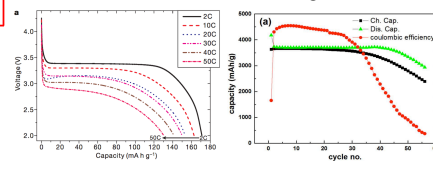
Introduction:

- Lithium-ion batteries are critical to modern and emerging technologies such as electric vehicles, high-power tools.
- It stores and release energy by Li-ion's diffusion between anode and cathode.

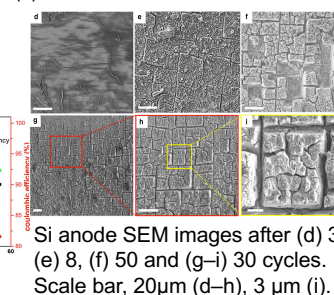


Current Problems of Li-ion battery

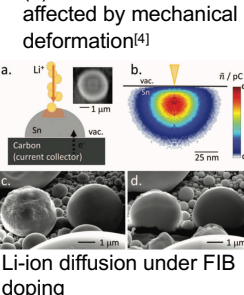
- (a) Poor power performance under high C-rate^[1]
- (b) Irreversible capacity loss after cycling and limited life time under high C-rate^[2]



(c) Electrodes' cracks and failure^[3]



(d) Li-ion diffusion were affected by mechanical deformation^[4]



Objective:

- Describe and predict electrical potential, capacity, stress and strain under high C-rate (dis)charging.
- Predict Li-ion battery performance under various C-rates.
- Develop approaches to improve Li-ion battery's cyclic life at high C-rate

Methods and Current Results

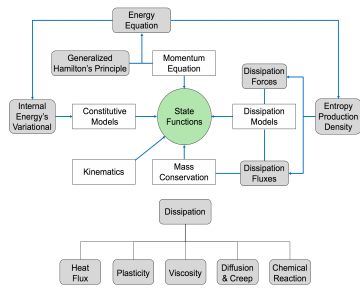
Model Architecture based on Continuum Mechanics and Non-Equilibrium Thermodynamics

Constitutive models

$$\dot{\Omega} = \dot{\Omega}(\lambda, G, \rho, g, \dot{\epsilon}^{(e)}, \sigma, \dot{\epsilon}, \kappa, x_{(k)}, \epsilon^{(e)})$$

$$\mu_{(12)} = \mu_{(12)}(x_{(k)}, \epsilon^{(e)}, \rho)$$

$$ds = \sum_j -\bar{\gamma}^{(j)} d\bar{\epsilon}_{(2)j}^{(l)} + c_{Vx} \frac{dT}{T} + \left(\frac{\partial s}{\partial x_{(k)}} \right)_{\epsilon_{(2)j}^{(l)}, T} dx_{(k)}$$



Momentum equation

$$\rho \frac{dv}{dt} = \nabla \cdot \mathbf{p} + \sum_k \rho_{(k)} \mathbf{F}_{(k)}$$

Mass conservation

$$\rho \frac{dx_{(k)}}{dt} + \nabla_j J_{(k)}^j = \sum_j \bar{\gamma}_{(k)}^{(j)} J_{(k)}^{(j)} \quad F \int_V J_M dV = I$$

Dissipation models

$$\lambda^{(p)\pm} = C^{(p)\pm} \exp\left(-\frac{E_A^{(p)\pm}}{RT}\right)$$

$$\tau^{(e)} = \tau^{(e)}(\dot{\epsilon}^{(e)}, \lambda^{(p)\pm})$$

$$J_{(k)} = -\frac{I^{(k)}}{T} - \nabla T - \sum_k \frac{I^{(k)}}{T} \cdot \nabla(\psi_{(k)} - \psi_{(s)}) - \frac{I^{(k)}}{T} \cdot \nabla \phi$$

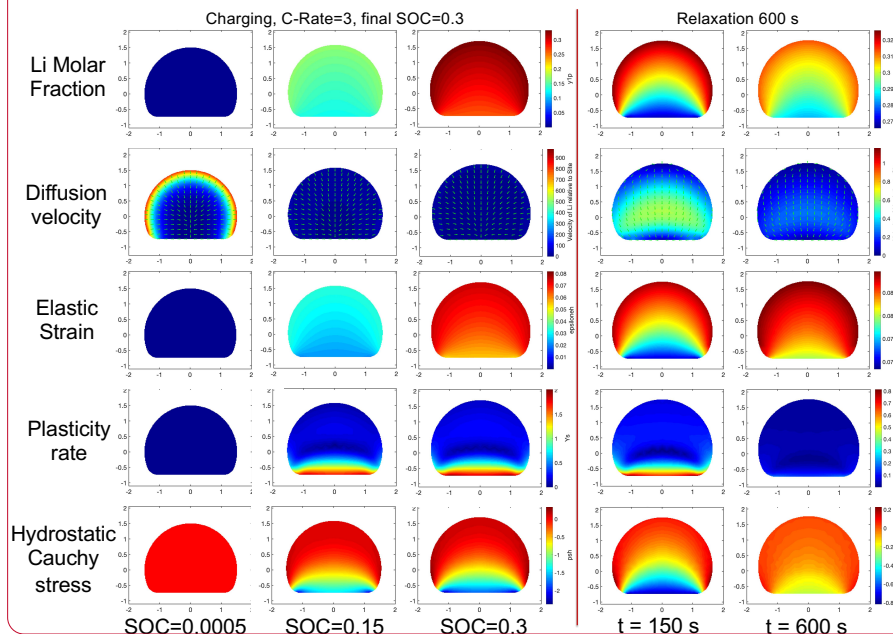
$$r_+^{(j)} = C_+^{(j)} \exp\left(\alpha^{(j)} \beta \sum_k \mu_{(k)M} \delta^{(k)j}\right)$$

Kinematics

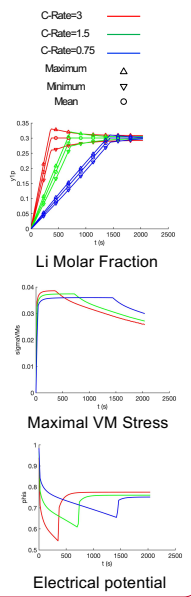
$$\dot{\epsilon}_{(2)ij} = \frac{\partial \epsilon_{(2)ij}}{\partial t} = \frac{1}{2} \frac{\partial g_{(2)ij}}{\partial t}$$

$$\dot{\epsilon}_{(2)ij} = \dot{\epsilon}_{ij}^{(e)} + \dot{\epsilon}_{ij}^{(p)} \quad \dot{\epsilon}_{(2)ij} = \frac{1}{2} (\nabla_j v_{(i)}^t + \nabla_i v_{(j)}^t)$$

Numerical Simulation



Evolution curves



Future Work

- Simulate whole (dis)charging process and cycling
- Use the finite different method to obtain stress evolutions with phase transformation during cycling.
- Developing algorithms to simulate continuous plasticity-elasticity interface. Damage and irreversible capacity loss modeling.